## ADJ USTABLE LED DRIVER WTTH INTERNAL SWITCH AND OPEN CIRCUIT PROTECTION IN SC70-6

## DESCRIPTION

The ZXLD1100 is a PFM inductive boost converter designed for driving 2, 3 or 4 series connected white LEDs from a Li-lon cell and up to 8 LEDs from a 5 V supply. The device operates from an input supply of between 2.5 V and 5.5 V and provides an adjustable output current of up to 50 mA .
The ZXLD1100 includes the output switch and peak current sense resistor, and can operate with a maximum output voltage of 28 V .

Quiescent current is typically $60 \mu \mathrm{~A}$ and a shutdown function is provided to reduce this current to less than 500nA in the 'off' state.

## ADVANCED FEATURES

- Internal 30V NDMOS switch, current sense and open circuit protection
- True Analog Dimming via PWM

FEATURES

- Low profile SC70 6 pin package
- Internal PWM filter for flicker free output
- High efficiency (80\% typ)
- Wide input voltage range: 2.5 V to 5.5 V
- Up to 50 mA output current
- Low quiescent current: ( $60 \mu \mathrm{~A}$ typ)
- 500nA maximum shutdown current
- Up to 1 MHz switching frequency
- Low external component count
- Inherently matched LED currents

PIN CONNECTIONS


Output current can be adjusted by applying a PWM control signal to the 'Enable' pin. Depending upon the control frequency, this will provide either a continuous or a 'chopped' output current. The PWM filter components are contained within the chip.
The ZXLD1100 contains an internal avalanche diode to protect the output switch. This allows the device to operate indefinitely if the load is open circuit. Input supply current during this condition is less than 1mA.

The device is assembled in a low profile SC70-6 pin package with industry standard pinout.

## APPLICATIONS

- Mobile phones
- Digital cameras
- PDAs
- LCD modules
- Portable internet appliances
- Palmtop computers

TYPICAL APPLICATION CIRCUIT

## ZXLD1100

ORDERING INFORMATION

| DEVICE | DEVICE DESCRIPTION | TEMPERATURE RANGE | PART MARK | TAPING <br> OPTIONS |
| :--- | :---: | :---: | :---: | :---: |
| ZXLD 1100 H 6 | Boost convertor in SC70-6 | -40 to $+85^{\circ} \mathrm{C}$ | 110 | TA, TC |

ZXLD1100H6TA $=7$ " reel of 3,000 devices
ZXLD1100H6TC $=13$ " reel of 10,000 devices

ABSOLUTE MAXIMUM RATINGS (Voltages to GND unless otherwise stated)

| PARAMETER | SYMBOL | LIMIT | UNIT |
| :--- | :--- | :---: | :---: |
| Input voltage | $\left(\mathrm{V}_{\text {IN }}\right)$ | 7 | V |
| LX output voltage | $\left(\mathrm{V}_{\mathrm{LX}}\right)$ | 30 | V |
| Switch output current | $\left(\mathrm{I}_{\mathrm{LX}}\right)$ | 500 | mA |
| Power dissipation | $(\mathrm{PD})$ | 300 | mW |
| Operating temperature | $\left(\mathrm{T}_{\mathrm{OP}}\right)$ | ${ }^{\circ} \mathrm{C}$ |  |
| Storage temperature | $\left(\mathrm{T}_{\text {ST }}\right)$ | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| J unction temperature | $\left(\mathrm{T}_{\mathrm{jMAX}}\right)$ | -55 to 150 | ${ }^{\circ} \mathrm{C}$ |

ELECTRICAL CHARACTERISTICS (at $\mathrm{V}_{\mathrm{IN}}=3 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$ unless otherwise stated ${ }^{(1)}$ )

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IN }}$ | Input voltage |  | 2.5 |  | 5.5 | V |
| $\mathrm{I}_{\mathrm{IN}}$ | Supply current <br> Quiescent <br> Shutdown | $V_{E N}=V_{I N}, I_{L X}=0,$ <br> Output not switching $\mathrm{V}_{\mathrm{EN}}=0 \mathrm{~V}$ |  | 60 | $\begin{aligned} & 100 \\ & 500 \end{aligned}$ | $\mu \mathrm{A}$ <br> nA |
| $\mathrm{V}_{\mathrm{FB}}$ | FB pin control voltage |  | 90.5 |  | 109.5 | mV |
| $\mathrm{I}_{\text {FB }}$ | FB pin input current |  |  |  | 100 | nA |
| $\mathrm{f}_{\text {LX }}$ | Operating frequency | $\begin{aligned} & \mathrm{L}=10 \mu \mathrm{H}, \mathrm{~V}_{\text {OUT }}=10 \mathrm{~V}, \\ & \mathrm{I}_{\text {OUT }}=20 \mathrm{~mA} \end{aligned}$ |  | 0.35 | 1 | MHz |
| T ${ }_{\text {OFF }}$ | LX output 'OFF' time |  | 350 | 500 |  | ns |
| Ton | LX output 'ON' time ${ }^{(2)}$ |  |  |  | 5 | $\mu \mathrm{s}$ |
| ${ }_{\text {LXPk }}$ | Switch peak current limit | $\begin{aligned} & \mathrm{L}=10 \mu \mathrm{H}, \mathrm{~V}_{\text {OUT }}=10 \mathrm{~V}, \\ & \mathrm{I}_{\text {OUT }}=20 \mathrm{~mA} \end{aligned}$ |  | 320 |  | mA |
| $\mathrm{R}_{\mathrm{LX}}$ | Switch 'On' resistance |  |  | 1.5 |  | $\Omega$ |
| LLX(leak) | Switch leakage current | $\mathrm{V}_{\mathrm{LX}}=20 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {OUT }}$ | Controller output voltage | Normal operation VSENSE pin open-circuit or grounded |  |  | 28 | V |
| $\mathrm{V}_{\text {OUT(MAX) }}$ | Controller output voltage with output open circuit ${ }^{(3)}$ | VSENSE connected to Vout | 25 | 30 |  | V |
| $\mathrm{V}_{\text {ENH }}$ | EN pin High level Input voltage | Device active | 1.5 |  | $\mathrm{V}_{\text {IN }}$ | V |
| $\mathrm{V}_{\text {ENL }}$ | EN pin Low level Input voltage | Device in shutdown |  |  | 0.4 | V |
| $\mathrm{I}_{\text {ENL }}$ | EN pin Low level input current | $\mathrm{V}_{\mathrm{EN}}=0 \mathrm{~V}$ |  |  | -100 | nA |
| IENH | EN pin High level input current | $\mathrm{V}_{\text {EN }}=\mathrm{V}_{\text {IN }}$ |  |  | 1 | $\mu \mathrm{A}$ |
| $\mathrm{T}_{\text {EN(hold) }}$ | EN pin turn off delay ${ }^{(4)}$ | $\mathrm{V}_{\text {EN }}$ switched from high to low |  | 120 |  | $\mu \mathrm{s}$ |
| $\Delta \mathrm{T} / \mathrm{T}$ | PWM duty cycle range at 'EN' input for filtered PWM control ${ }^{(5)}$ | $\begin{aligned} & 10 \mathrm{kHz}<\mathrm{f}<100 \mathrm{kHz}, \\ & \mathrm{~V}_{\mathrm{ENH}}=\mathrm{V}_{\mathrm{IN}} \end{aligned}$ | 20 |  | 100 | \% |
| $\mathrm{f}_{\text {LPF }}$ | Internal PWM low pass filter cut-off frequency |  |  | 4 |  | kHz |
| $\mathrm{A}_{\text {LPF }}$ | Filter attenuation | $\mathrm{f}=30 \mathrm{kHz}$ |  | 52.5 |  | dB |

NOTES:
(1) Production testing of the device is performed at $25^{\circ} \mathrm{C}$. Functional operation of the device over a $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range is guaranteed by design, characterization and process control.
(2) Nominal 'on' time (TONnom) is defined by the input voltage ( $\mathrm{V}_{\mathrm{IN}}$ ), coil inductance $(\mathrm{L})$ and peak current (llXpkdc) according to the expression: TONnom $=\left\{\right.$ LX (pkdc) $\times$ LN $\left.N_{I N}\right\}+200 \mathrm{~ns}$.
(3) When using the open circuit protection feature, the maximum output voltage under normal operation should be maintained below the minimum value specified, in order to prevent possible disturbance of the current control loop
(4) This is the time for which the device remains active after the EN pin has been asserted low. This delay is necessary to allow the output to be maintained during dc PWM mode operation.
(5) The minimum PWM signal frequency during this mode of operation is to ensure that the device remains active during PWM control. This provides a continuous dc output current. For lower frequencies, the device will be gated 'on' and 'off' during PWM control.
(6) The maximum PWM signal frequency during this mode of operation should be kept as low as possible to minimize errors due to the turn-off delay of the device (see Enable pin turn-off delay).

## ZXLD1100

## PIN DESCRIPTION

| PIN NO. | NAME | DESCRIPTION |
| :--- | :--- | :--- |
| 1 | LX | Output of NDM OS switch |
| 2 | GND | Ground (OV) |
| 3 | FB | Feedback pin for current control loop (connect resistor R1 <br> from this pin to GND for output current I=100mV/R1) |
| 4 | EN | Enable input (active high to turn on device) <br> Also used to adjust output current by PWM signal. <br> Connect to $\mathrm{V}_{\text {in }}$ for permanent operation. |
| 5 | $\mathrm{~V}_{\text {IN }}$ | Output voltage sense (used for open circuit protection). <br> Connect to GND if not required. |
| 6 | Input voltage (2.5V to 5.5V). Decouple with capacitor close <br> to device. |  |

## BLOCK DIAGRAM



ISSUE 4-J ULY 2004

## DEVICE DESCRIPTION

The device is a PFM flyback dc-dc boost converter, working in discontinuous mode.

With reference to the chip block diagram and typical application circuit, the operation of the device is as follows:

## Control loop

When 'EN' is high, the control circuits become active and the low side of the coil (L1) is switched to ground via NDMOS transistor (MN). The current in L1 is allowed to build up to an internally defined level (nominally 320 mA ) before MN is turned off. The energy stored in L1 is then transferred to the output capacitor (C2) via schottky diode (D1). When the voltage on C2 has risen above the threshold voltage of the series connected LEDs, current will flow through external sense resistor R1. The voltage developed across R1 is sensed at pin 'FB' and compared to a 100 mV reference voltage ( $\mathrm{V}_{\text {REF }}$ ). A comparator senses when the feedback voltage is above $V_{\text {REF }}$ and its output is used to control the 'off' time of the output switch. The control loop is self-oscillating, producing pulses of up to $5 \mu \mathrm{~s}$ maximum duration (switch 'on'), at a frequency that varies in proportion to the LED current. The feedback loop maintains a voltage of $V_{\text {REF }}$ at the FB pin and therefore defines a maximum LED current equal to $V_{\text {REF }}$ divided by R1. The minimum 'off' time of the output switch is fixed at $0.5 \mu \mathrm{~s}$ nominal, to allow time for the coil's energy to be dissipated before the switch is turned on again. This maintains stable and efficient operation in discontinuous mode.

## Open circuit protection

There is an internal avalanche diode between the $V_{\text {SENSE }}$ and FB pins of the device. This diode, together with the associated resistors provides open circuit protection when the $V_{\text {SENSE }}$ pin is connected to the output voltage. In the event of an open circuit condition, the output voltage will rise above the breakdown voltage of the internal diode, which will then conduct and override the control signal from the current sense resistor. This maintains the output voltage at a level below the breakdown voltage of the output switch. Supply current in this condition will fall to a low value as the control loop provides only the bias current for the diode.

## Filtered PWM operation

The input of an internal low pass filter is switched to $V_{\text {REF }}$ when the EN pin is high and switched to ground when the EN pin is low. The output of this filter drives the comparator within the control loop. A continuous high state on EN therefore provides a filtered voltage of value $V_{\text {REF }}$ to the comparator. However, by varying the duty cycle of the EN signal at a suitably high frequency ( $\mathrm{f}>10 \mathrm{kHz}$ ), the control loop will see a voltage, that has an average value equal to the duty cycle multiplied by $V_{\text {REF }}$. This provides a means of adjusting the output current to a lower value. It also allows the device to be both turned on and adjusted with a single signal at the 'EN' pin. The output during this mode of operation will be a dc current equal to (VREF/R1) x duty cycle

## Gated PWM operation

The internal circuitry of the ZXLD1100 is turned off when no signal is present on the 'EN' pin for more than $120 \mu \mathrm{~s}$ (nominal). A low frequency signal applied to the EN pin will therefore gate the device 'on' and 'off' at the gating frequency and the duty cycle of this signal can be varied to provide a 'chopped' output current equal to ($V_{\text {REF }} / R 1$ ) x duty cycle. For best accuracy, the gating frequency should be made as low as possible (e.g. below 1 kHz ), such that the turn off delay of the chip is only a small proportion of the gating period

Further details of setting output current are given in the applications section under brightness control.

## ZXLD1100

TYPICAL CHARACTERISTICS
(For typical application circuit at $\mathrm{V}_{\text {IN }}=3 \mathrm{~V}$ and $\mathrm{TA}=25^{\circ} \mathrm{C}$ unless otherwise stated)


ISSUE 4 - J ULY 2004

## ZXLD1100

TYPICAL OPERATING CHARACTERISTICS
(For typical applications circuit at $\mathrm{V}_{\mathrm{IN}}=3 \mathrm{~V}, \mathrm{~L}=10 \mu \mathrm{H}$ Coilcraft DO1608C Series, 3 series LEDs, $l_{\text {LED }}=15 \mathrm{~mA}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ unless otherwise stated)


## ZXLD1100

## APPLICATIONS

## Programming the maximum LED current

The maximum LED current is programmed by adding a single resistor in series with the LED chain. The current is determined by the resistor value and feedback voltage and is given by:

$$
\begin{aligned}
& \mathrm{I}_{\mathrm{LED}}=\mathrm{V}_{\mathrm{FB}} / \mathrm{R} 1 \\
& \text { where } \mathrm{V}_{\mathrm{FB}}=100 \mathrm{mV}
\end{aligned}
$$

The table below gives recommended resistor values for required LED currents:

| LED Current | R1 Value |
| :--- | :--- |
| 10 mA | $10 \Omega$ |
| 15 mA | $6.8 \Omega$ |
| 20 mA | $5 \Omega$ |
| 30 mA | $3.3 \Omega$ |

## Dimming Control via a PWM signal on the EN pin

A Pulse Width Modulated (PWM) signal can be applied to the EN pin in order to adjust the output current to a value below the maximum LED current. Two modes of adjustment are possible as described below.

## True Analog Dimming - Filtered 'DC' mode

If a PWM signal of 10 kHz or higher is applied to the EN pin, the device will remain active when the EN pin is low. However, the input to the internal low pass filter will be switched alternately from $\mathrm{V}_{\text {REF }}$ to ground, with a duty cycle (D) corresponding to that of the PWM signal. This will present a filtered dc voltage equal to the duty cycle multiplied by $\mathrm{V}_{\text {ref }}$ to the control loop and will produce a dc output current lower than the maximum set value. This current is given by:

$$
\text { loutdc }=0.1 \mathrm{D} / \mathrm{R} 1
$$

This mode of adjustment minimizes flicker in the light output and system noise.

## Pulsed Dimming - Gated Mode

If a lower frequency of 1 kHz or less is applied to the EN pin, the device will be gated 'on' and 'off' at a duty cycle (D) corresponding to that of the input signal. The average output current is then given by:

$$
\text { louTavg } \approx 0.1 \mathrm{D} / \mathrm{R} 1
$$

This mode may be preferred over dc current control if the purest white output is required. However, note the $120 \mu \mathrm{~s}$ nominal turn-off delay of the device, when using the device in this mode.

## Dimming Control using a DC voltage

For applications where the EN pin is not available a DC voltage can be used to control dimming. By adding resistors R2 and R3 and applying a DC voltage, the LED current can be adjusted from $100 \%$ to $0 \%$. As the DC voltage increases, the voltage drop across R2 increases and the voltage drop across R1 decreases, thus reducing the current through the LEDs. Selection of R2 and R3 should ensure that the current from the DC voltage is much less than the LED current and much larger than the feedback current. The component values in the diagram below represent 0\% to $100 \%$ dimming control from a 0 to 2 V DC voltage.


## Dimming Control using a logic signal

For applications where the LED current needs to be adjusted in discrete steps a logic signal can be applied as shown in the diagram below. When Q1 os 'off', R1 sets the minimum LED current. When Q1 is 'on', R2 sets the LED current that will be added to the minimum LED current. The formula for selecting values for R1 and R2 are given below:


MOSFET 'off'

$$
I_{\text {LED(MIN) }} \frac{V_{F B}}{R_{L E D}}
$$

MOSFET ‘on’
$I_{\text {LED(MAX) }} \frac{V_{F B}}{R_{\text {LED }}} I_{\text {LED(MIN })}$
where $\mathrm{V}_{\mathrm{FB}}=100 \mathrm{mV}$

ISSUE 4 - J ULY 2004

## Open circuit protection

The voltage sense pin (VSENSE) can be connected to the output to provide open circuit protection for the device and external circuits when driving series connected LEDs, thus eliminating the need for an external Zener diode. Protection is provided by the internal avalanche diode (ZD), which limits the maximum output voltage to a value below the breakdown voltage of the output switch when the connection to the diodes is broken.

## Capacitor selection

A ceramic capacitor grounded close to the GND pin of the package is recommended at the output of the device. Surface mount types offer the best performance due to their lower inductance. A minimum value of $0.22 \mu \mathrm{~F}$ is advised, although higher values will lower switching frequency and improve efficiency especially at lower load currents. A higher value will also minimize ripple when using the device to provide an adjustable dc output current.

A good quality, low ESR capacitor should also be used for input decoupling, as the ESR of this capacitor is effectively in series with the source impedance and lowers overall efficiency. This capacitor has to supply the relatively high peak current to the coil and smooth the current ripple on the input supply. A minimum value of $1 \mu \mathrm{~F}$ is acceptable if the input source is close to the device, buthigher values will improve performance at lower input voltages, when the source impedance is high. The input capacitor should be mounted as close as possible to the IC

For maximum stability over temperature, capacitors with $\times 7$ R dielectric are recommended, as these have a much smaller temperature coefficient than other types.

A table of recommended manufacturers is provided below:

| Manufacturer | Website |
| :--- | :--- |
| Murata | www.murata.com |
| Taiyo Yuden | www.t-yuden.com |
| Kemet | www.kement.com |
| AVX | www.avxcorp.com |

## ZXLD1100

## Inductor selection

The choice of inductor will depend on available board space as well as required performance. Small value inductors have the advantage of smaller physical size and may offer lower series resistance and higher saturation current compared to larger values. A disadvantage of lower inductor values is that they result in higher frequency switching, which in turn causes reduced efficiency due to switch losses. Higher inductor values can provide better performance at lower supply voltages. However, if the inductance is too high, the output power will be limited by the internal oscillator, which will prevent the coil current from reaching its peak value. This condition will arise whenever the ramp time (lLX(peak) $\times \mathrm{L} / \mathrm{V}_{\mathrm{IN}}$ ) exceeds the nominal $5 \mu \mathrm{~s}$ maximum 'on' time limit for the LX output.

The graphs opposite show the ZXLD1100 performance forgiven inductor values and different manufacturers.

Recommended inductor values for the ZXLD1100 are in the range $6.8 \mu \mathrm{H}$ to $22 \mu \mathrm{H}$. The inductor should be mounted as close to the device as possible with low resistance connections to the LX and VIN pins.

Suitable coils for use with the ZXLD1100 are shown in the table below:

| Part No. | $\mathbf{L}$ <br> $(\mu \mathbf{H})$ | DCR <br> $(\Omega)$ | $\mathbf{I}_{\text {SAT }}$ <br> $(\mathbf{A})$ | Manufacturer |
| :--- | :--- | :--- | :--- | :--- |
| CM D4D11-100MC | 10 | 0.457 | 0.5 | Sumida <br> www.sumida.com |
| DO1608-103 | 10 | 0.16 | 1.1 | Coilcraft <br> www.coilcraft.com |
| LQH31CN100 | 10 | 1.3 | 0.23 | Murata <br> www.murata.com |
| LB2012Y100MR | 10 | 0.5 | 0.1 | Taiyo Yuden <br> www.t-yuden.com |



## Diode selection

The rectifier diode (D1) should be a fast low capacitance schottky diode with low reverse leakage at the working voltage. It should also have a peak current rating above the peak coil current and a continuous current rating higher than the maximum output load current.

The table below gives some typical characteristics for diodes that can be used with the ZXLD1100:

## Layout considerations

PCB tracks should be kept as short as possible to minimize ground bounce, and the ground pin of the device should be soldered directly to the ground plane. It is particularly important to mount the coil and the input/output capacitors close to the device to minimize parasitic resistance and inductance, which will degrade efficiency. The FB pin is a high impedance input so PCB track lengths to this should also be kept as short as possible to reduce noise pickup. Excess capacitance from the FB pin to ground should be avoided.

| Diode | $\mathbf{V}_{\mathbf{F}}$ @ 100mA (mV) | $\mathbf{I}_{\mathbf{F S M}}(\mathbf{m A})$ | $\mathbf{l c}(\mathbf{m A})$ | $\mathbf{I}_{\mathbf{R}}$ at 30V $(\boldsymbol{\mu A )}$ | Package |
| :--- | :--- | :--- | :--- | :--- | :--- |
| ZHCS400 | 300 | 1000 | 400 | 15 | SOD323 |
| ZHCS500 | 300 | 1000 | 500 | 15 | SOT23 |

## REFERENCE DESIGNS

## 3 LED Driver for Handset LCD Backlight

## Circuit Diagram



Note: LED current is set to 15 mA

## Bill of materials

| Ref | Value | Package | Part Number | Manufacturer | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- |
| U1 |  | SC70-6 | ZXLD1100H6 | Zetex | LED Driver IC |
| D1 | 400 mA | SOD323 | ZHCS400 | Zetex | 400 mA Schottky Diode |
| L1 | $10 \mu \mathrm{H}$ |  | CMD4D11-100MC | Sumida | 1mm Height Profile |
| R1 | $6.8 \Omega$ | 0603 | Generic | Generic |  |
| R2 $^{1}$ | $100 \mathrm{k} \Omega$ | 0603 | Generic | Generic |  |
| C1 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| C2 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| LEDs |  |  | NSCW215 | Nichia | 3pcs per board |

Note: R2 is optional. If EN is floating add R2 to shutdown the ZXLD1100 and LEDs. If EN pin can be driven low, R2 is not necessary.

## Performance Graphs



## ZXLD1100

## 4 LED Driver for Handset LCD Backlight

## Circuit Diagram



Note: LED current is set to 15 mA

Bill of materials

| Ref | Value | Package | Part Number | Manufacturer | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- |
| U1 |  | SC70-6 | ZXLD1100H6 | Zetex | LED Driver IC |
| D1 | 400 mA | SOD323 | ZHCS400 | Zetex | 400 mA Schottky Diode |
| L1 | $10 \mu \mathrm{H}$ |  | CMD4D11-100MC | Sumida | 1mm Height Profile |
| R1 | $6.8 \Omega$ | 0603 | Generic | Generic |  |
| R2 $^{1}$ | $100 \mathrm{k} \Omega$ | 0603 | Generic | Generic |  |
| C1 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| C2 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| LEDs |  |  | NSCW215 | Nichia | 4pcs per board |

Note: R2 is optional. If EN is floating add R2 to shutdown the ZXLD1100 and LEDs. If EN pin can be driven low, R2 is not necessary.

## Performance Graphs



Efficiency vs Input Voltage


Efficiency vs Input Voltage

## 5 LED Driver for Handset Main and Sub Display LCD Backlight

## Circuit Diagram



Note: LED current is set to 15 mA

## Bill of materials

| Ref | Value | Package | Part Number | Manufacturer | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- |
| U1 |  | SC70-6 | ZXLD1100H6 | Zetex | LED Driver IC |
| D1 | 400 mA | SOD323 | ZHCS400 | Zetex | 400 mA Schottky Diode |
| L1 | $10 \mu \mathrm{H}$ |  | CMD4D11-100MC | Sumida | 1mm Height Profile |
| R1 | $6.8 \Omega$ | 0603 | Generic | Generic |  |
| R2 $^{1}$ | $100 \mathrm{k} \Omega$ | 0603 | Generic | Generic |  |
| C1 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| C2 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| LEDs |  |  | NSCW215 | Nichia | 5pcs per board |

Note: R 2 is optional. If EN is floating add R 2 to shutdown the $\mathrm{ZXLD1100}$ and LEDs. If EN pin can be driven low, R 2 is not necessary.

## Performance Graphs



Efficiency vs Input Voltage


Efficiency vs Input Voltage

## ZXLD1100

## 6 LED Driver for LCD Backlight

## Circuit Diagram



Note: LED current is set to 15 mA

Bill of materials

| Ref | Value | Package | Part Number | Manufacturer | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- |
| U1 |  | SC70-6 | ZXLD1100H6 | Zetex | LED Driver IC |
| D1 | 400 mA | SOD323 | ZHCS400 | Zetex | 400 mA Schottky Diode |
| L1 | $10 \mu \mathrm{H}$ |  | CMD4D11-100MC | Sumida | 1mm Height Profile |
| R1 | $6.8 \Omega$ | 0603 | Generic | Generic |  |
| R2 $^{1}$ | $100 \mathrm{k} \Omega$ | 0603 | Generic | Generic |  |
| C1 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| C2 | $1 \mu \mathrm{~F}$ | 0603 | Generic | Generic |  |
| LEDs |  |  | NSCW215 | Nichia | 6pcs per board |

Note: R2 is optional. If EN is floating add R2 to shutdown the ZXLD1100 and LEDs. If EN pin can be driven low, R2 is not necessary.

## Performance Graphs



ISSUE 4 - J ULY 2004

## ZXLD1100

## ZXLD1100

## PACKAGE OUTLINE - SC70-6



Controlling dimensions are in millimeters. Approximate conversions are given in inches

## PACKAGE DIMENSIONS

| DIM | Millimeters |  | Inches |  | DIM | Millimeters |  | Inches |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Max | Min | Max |  | Min | Max | Min | Max |
| A | 0.80 | 1.10 | 0.0315 | 0.0433 | E | 2.10BSC |  | 0.0826 BSC |  |
| A1 | - | 0.10 | - | 0.0039 | E1 | 1.25 | 1.35 | 0.0492 | 0.0531 |
| A2 | 0.80 | 1.00 | 0.0315 | 0.0394 | e | 0.65 BSC |  | 0.0255 BSC |  |
| b | 0.15 | 0.30 | 0.006 | 0.0118 | e1 |  |  | 0.051 | BSC |
| C | 0.08 | 0.25 | 0.0031 | 0.0098 | L | 0.26 | 0.46 | 0.0102 | 0.0181 |
| D | 2.00 BSC |  | 0.0787 BSC |  | $\mathrm{a}^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ |

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